

# Game Theory, Evolutionary Dynamics, and Multi-Agent Learning

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# Game theory

# Game theory: basics

## Normal form

- Players
- Actions
- Outcomes
- Utilities
- Strategies
- Solutions


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- **Players**
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		Player 2			
Player 1					

# Game theory: basics

Normal form

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		Player 2		
		Rock	Paper	Scissors
Player 1	Rock			
	Paper			
	Scissors			

# Game theory: basics

Normal form

- Players
- Actions
- **Outcomes**
- Utilities
- Strategies
- Solutions

		Player 2		
		Rock	Paper	Scissors
Player 1	Rock	Tie	Player 2 wins	Player 1 wins
	Paper	Player 1 wins	Tie	Player 2 wins
	Scissors	Player 2 wins	Player 1 wins	Tie

# Game theory: basics

Normal form

- Players
- Actions
- Outcomes
- **Utilities**
- Strategies
- Solutions

		Player 2		
		Rock	Paper	Scissors
Player 1	Rock	0,0	-1,1	1,-1
	Paper	1,-1	0,0	-1,1
	Scissors	-1,1	1,-1	0,0

# Game theory: basics

Normal form

- Players
- Actions
- Outcomes
- Utilities
- **Strategies**
- Solutions

		Player 2			
		Rock	Paper	Scissors	
Player 1	Rock	0,0	-1,1	1,-1	$\sigma_1(\text{Rock})$
	Paper	1,-1	0,0	-1,1	$\sigma_1(\text{Paper})$
	Scissors	-1,1	1,-1	0,0	$\sigma_1(\text{Scissors})$
		$\sigma_2(\text{Rock})$	$\sigma_2(\text{Paper})$	$\sigma_2(\text{Scissors})$	



# Game theory: basics

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- **Solutions**

		Player 2			
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	Paper	1,-1	0,0	-1,1	1/3
	Scissors	-1,1	1,-1	0,0	1/3
		1/3	1/3	1/3	

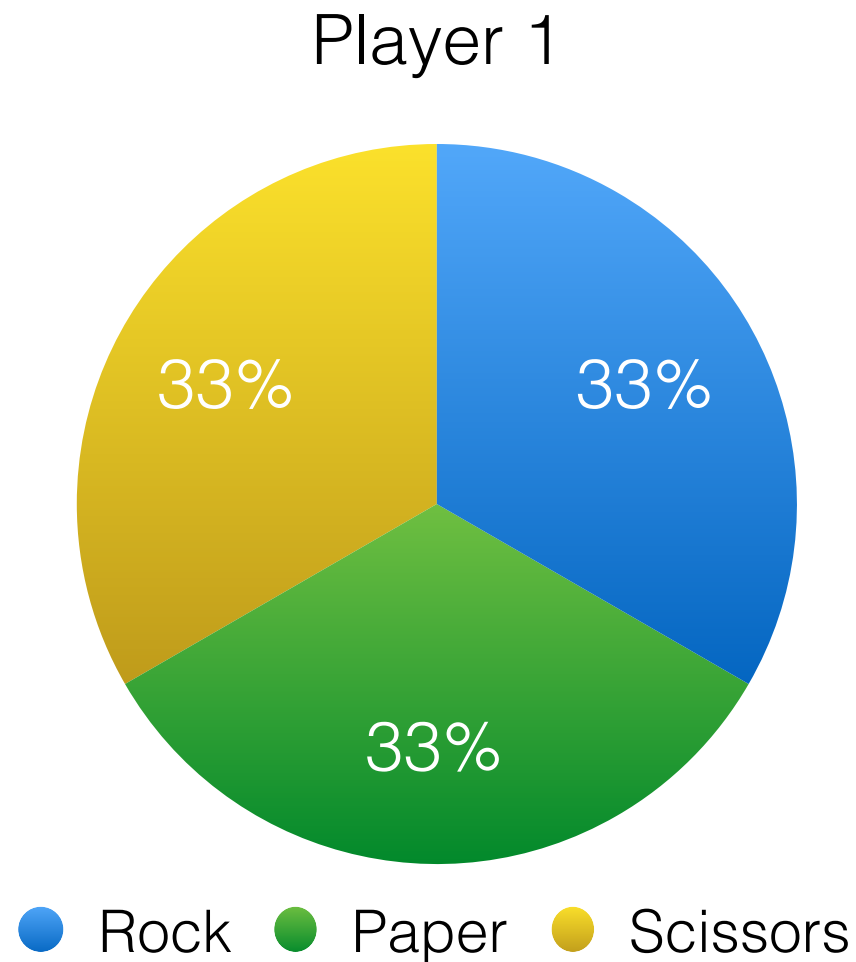
# Nash Equilibrium

A strategy profile  $(\sigma_1^*, \sigma_2^*)$  is a Nash equilibrium if and if:

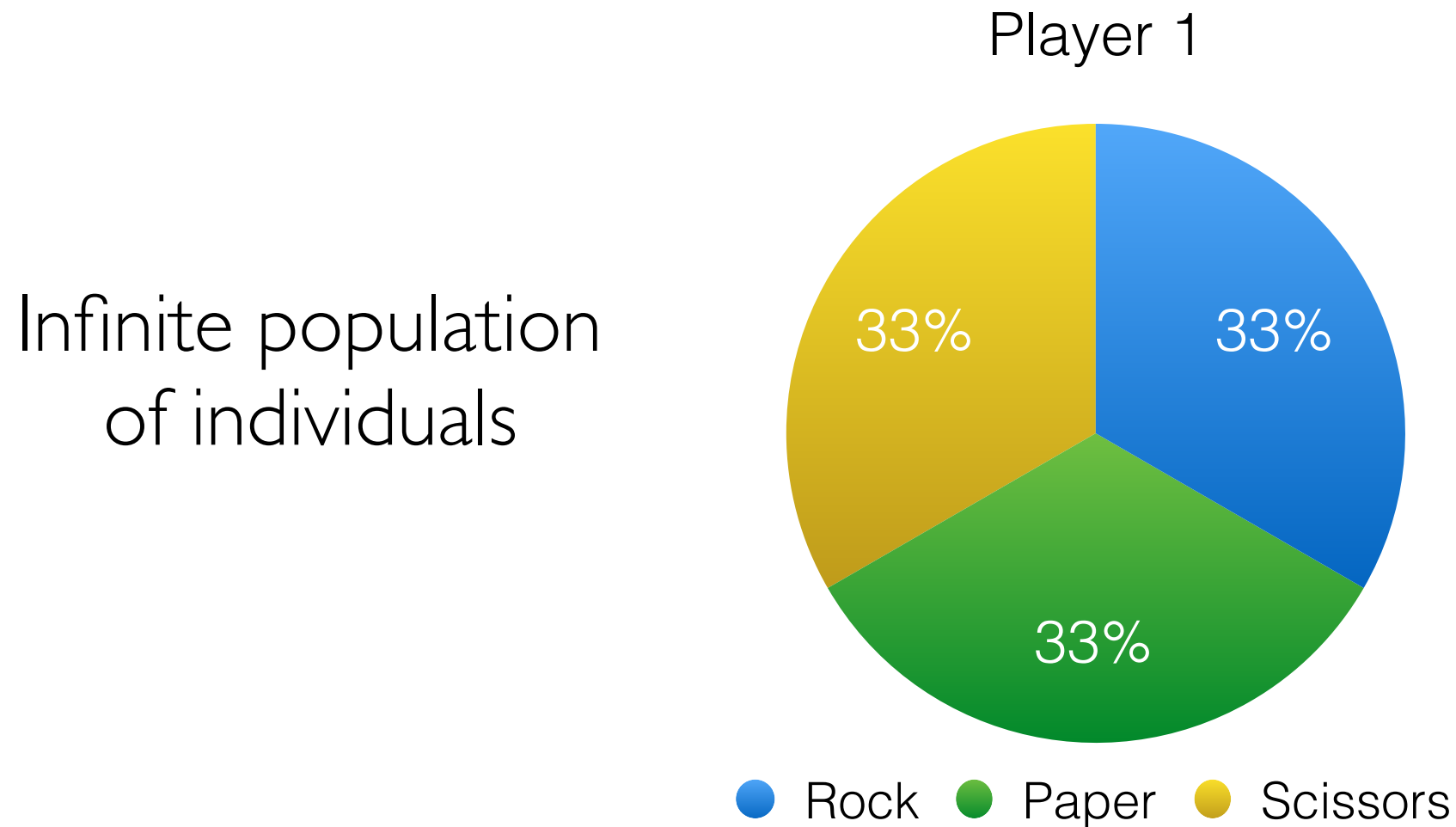
- $\sigma_1^* \in \arg \max_{\sigma_1} \left\{ \sigma_1 U_1 \sigma_2^* \right\}$
- $\sigma_2^* \in \arg \max_{\sigma_2} \left\{ \sigma_1^* U_2 \sigma_2 \right\}$

# Evolutionary dynamics

# An evolutionary interpretation



# An evolutionary interpretation





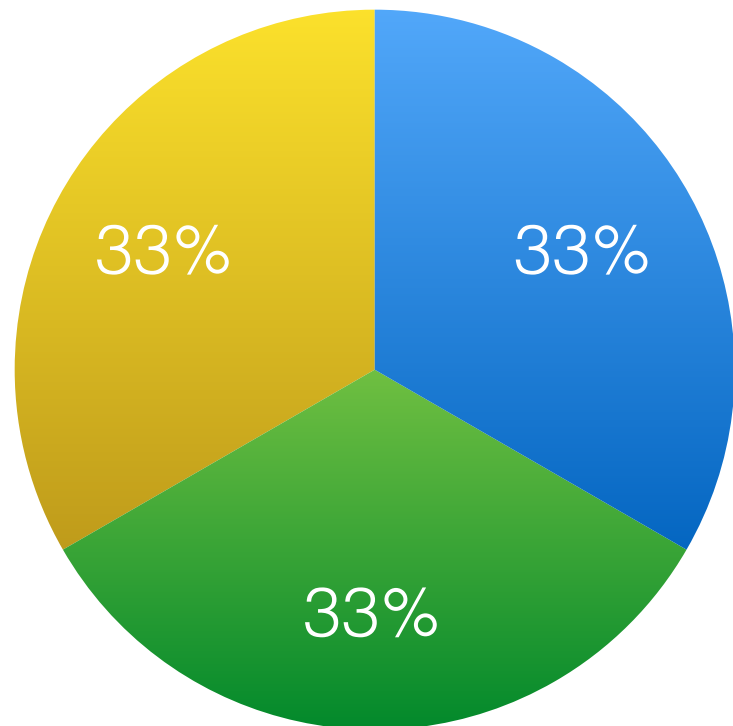


# Bacteria



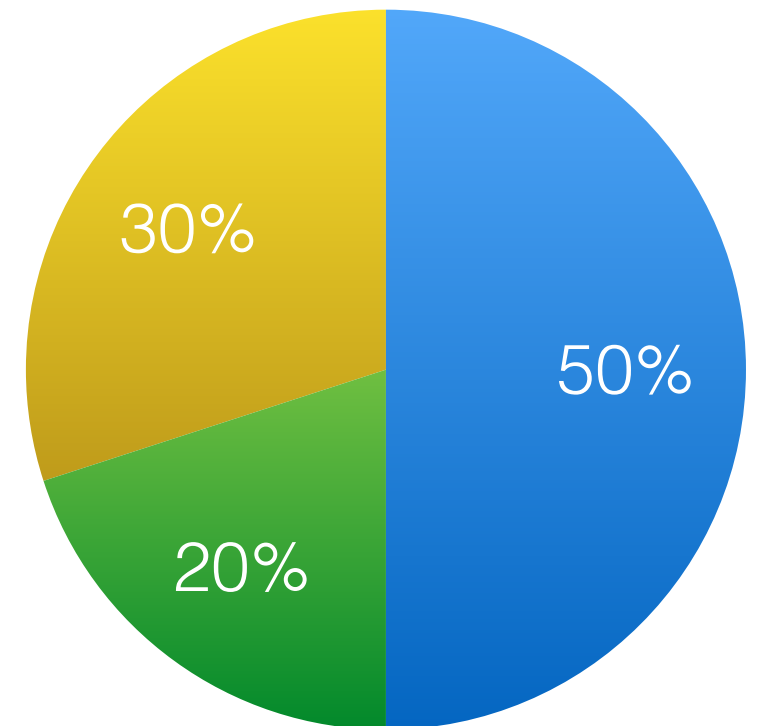
# An evolutionary interpretation

Player 1



● Rock ● Paper ● Scissors

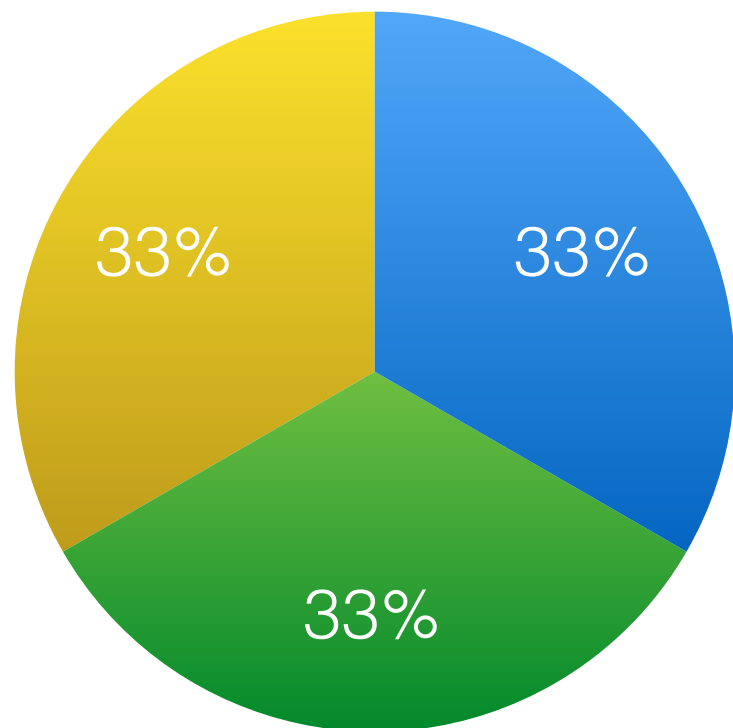
Player 2



● Rock ● Paper ● Scissors

# An evolutionary interpretation

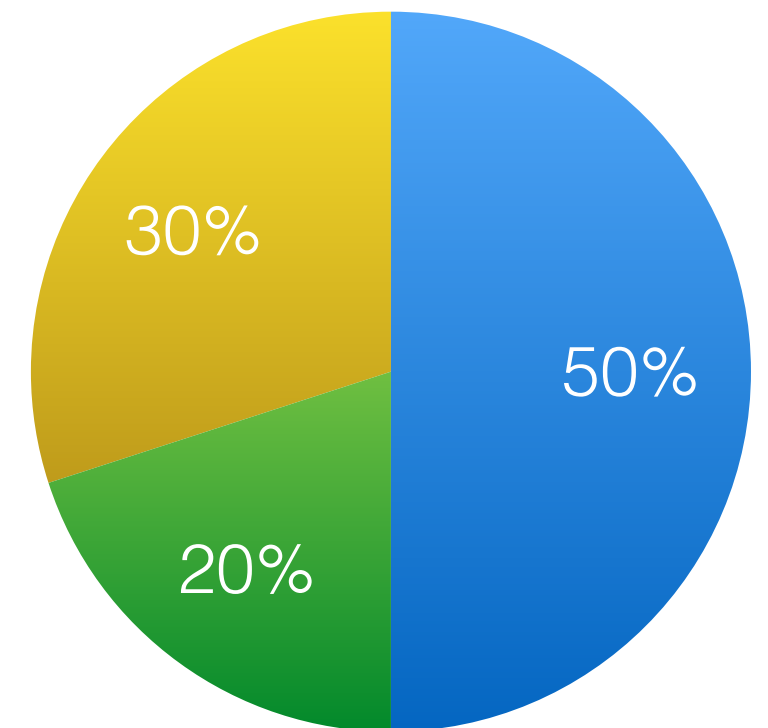
Player 1



● Rock ● Paper ● Scissors

	Rock	Paper	Scissors
Rock	0,0	-1,1	1,-1
Paper	1,-1	0,0	-1,1
Scissors	-1,1	1,-1	0,0

Player 2

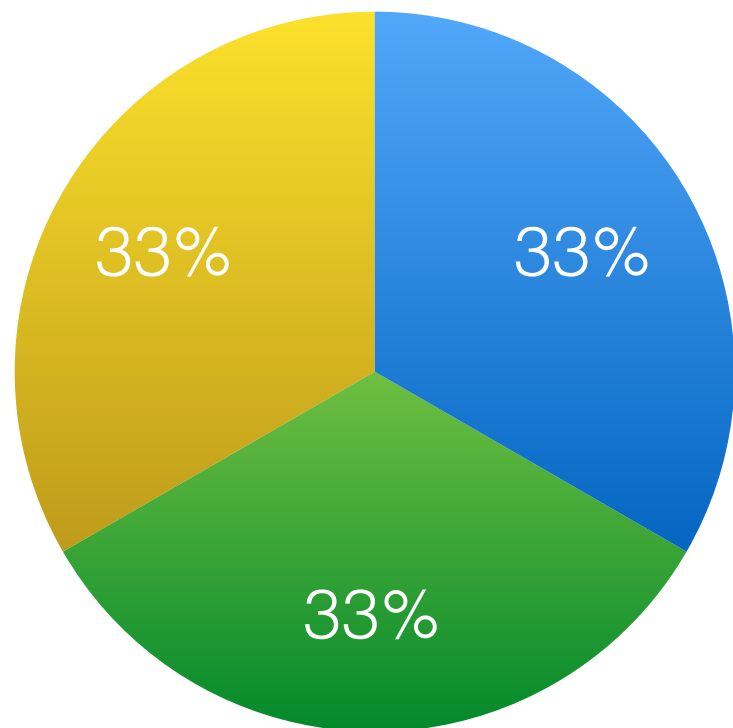


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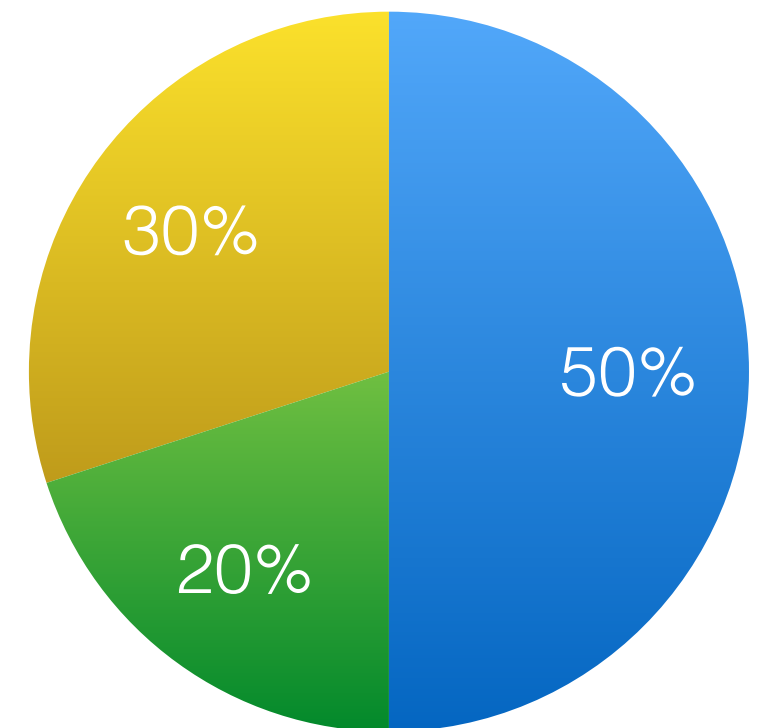
# An evolutionary interpretation

Player 1



● Rock ● Paper ● Scissors

Player 2



● Rock ● Paper ● Scissors

	Rock	Paper	Scissors
Rock	0,0	-1,1	1,-1
Paper	1,-1	0,0	-1,1
Scissors	-1,1	1,-1	0,0

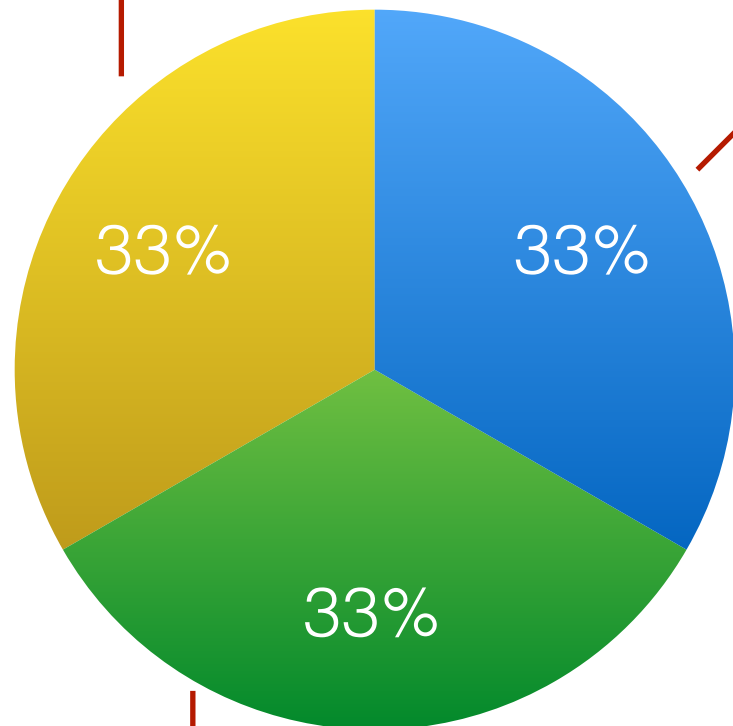
At each round, each individual of a population plays against each individual of the opponent's population

# An evolutionary interpretation

Utility = -0.3

Player 1

Utility = 0.1

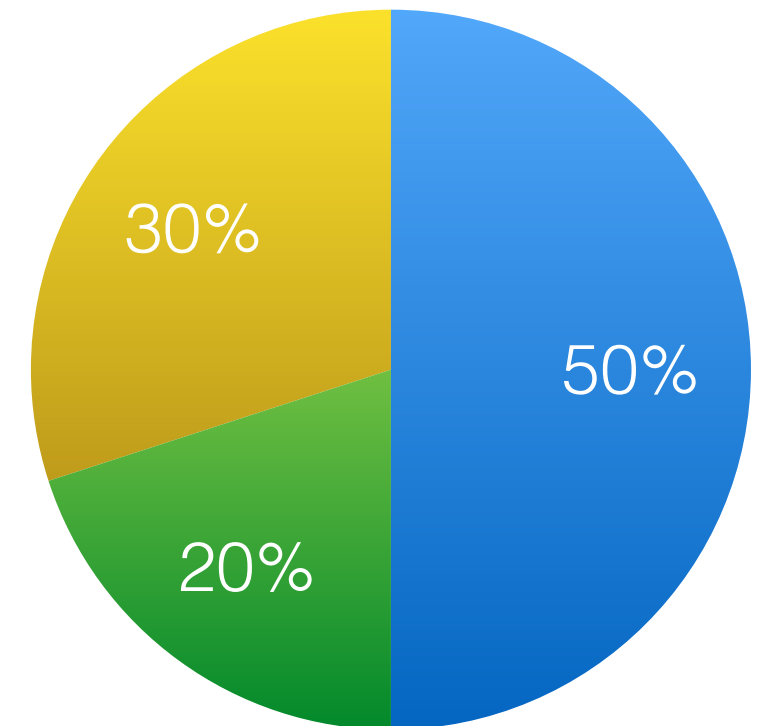


● Rock ● Paper ● Scissors

Utility = 0.2

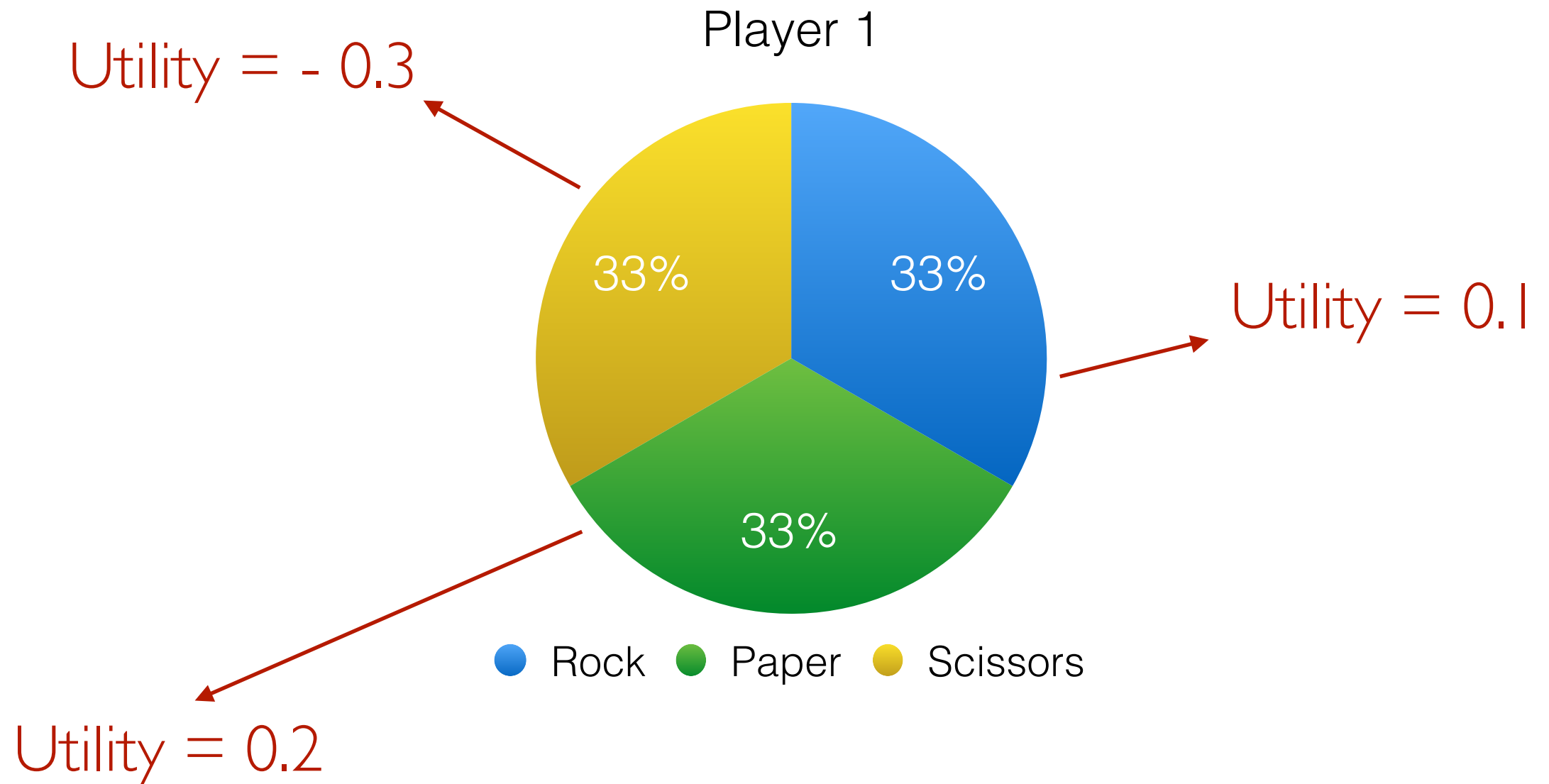
	Rock	Paper	Scissors
Rock	0,0	-1,1	1,-1
Paper	1,-1	0,0	-1,1
Scissors	-1,1	1,-1	0,0

Player 2

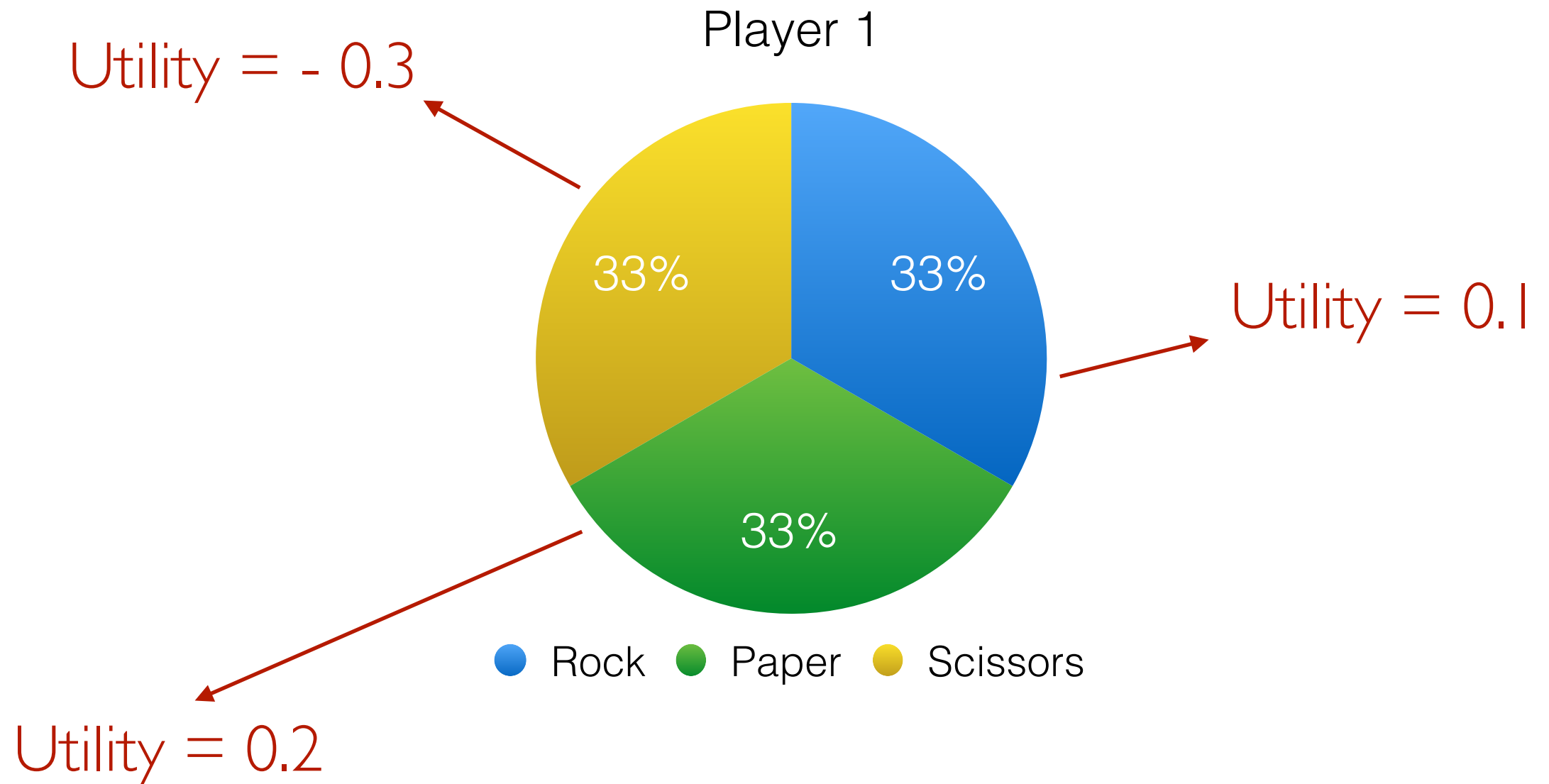


● Rock ● Paper ● Scissors

# An evolutionary interpretation

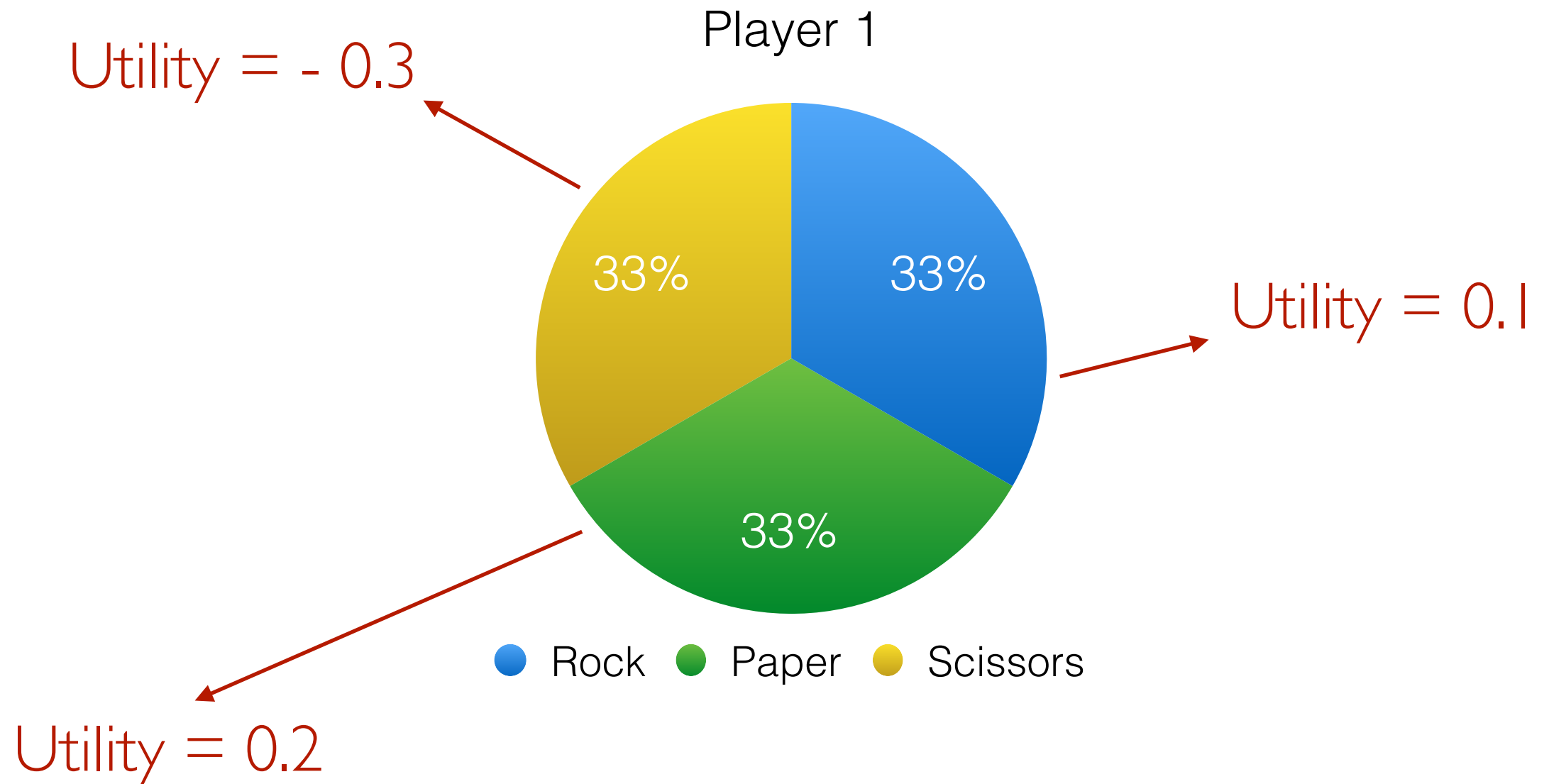


# An evolutionary interpretation



The average utility is 0

# An evolutionary interpretation

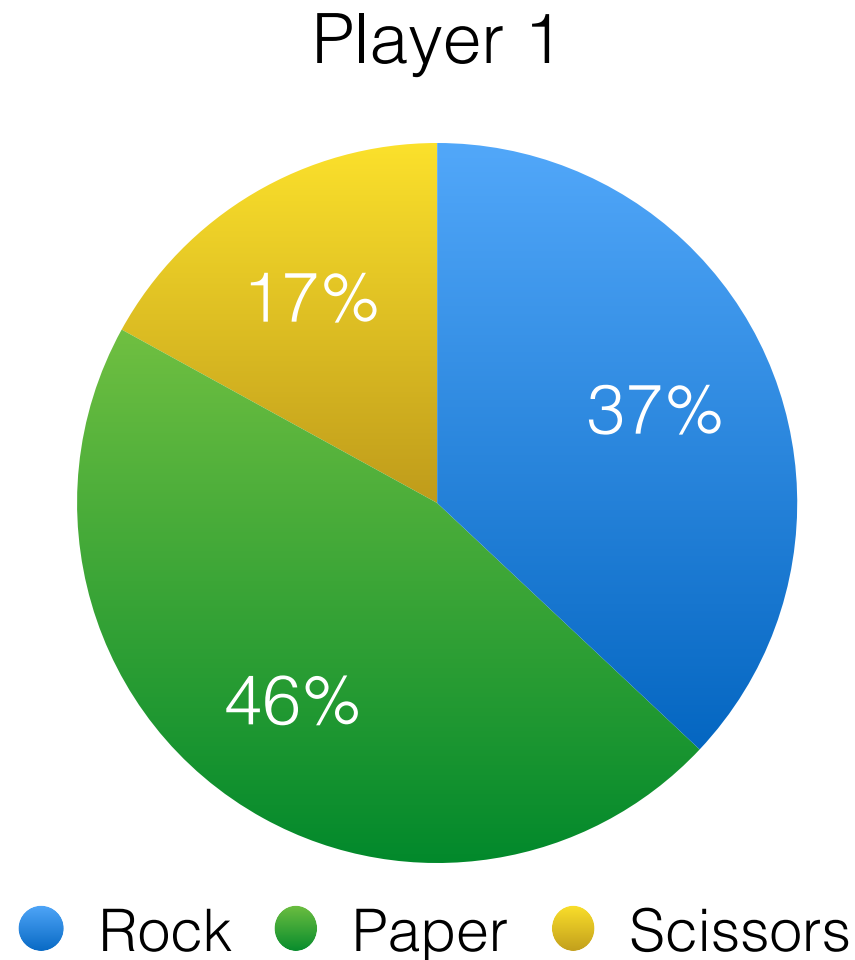


The average utility is 0

A **positive** ( $utility - average\ utility$ ) leads to an **increase** of the population

A **negative** ( $utility - average\ utility$ ) leads to a **decrease** of the population

# An evolutionary interpretation



New population after the replication

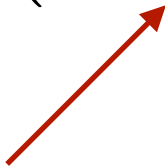
# Revision protocol

**Question:** how the populations change?

Replicator dynamics

$$\dot{\sigma}_1(a, t) = \sigma_1(a, t) \left( e_a U_1 \sigma_2(t) - \sigma_1(t) U_1 \sigma_2(t) \right)$$

Utility given by playing  $a$   
with a probability of  $1$



Average population utility



# Evolutionary Stable Strategies

*A strategy is an ESS if it is immune to invasion by mutant strategies, given that the mutants initially occupy a small fraction of population*

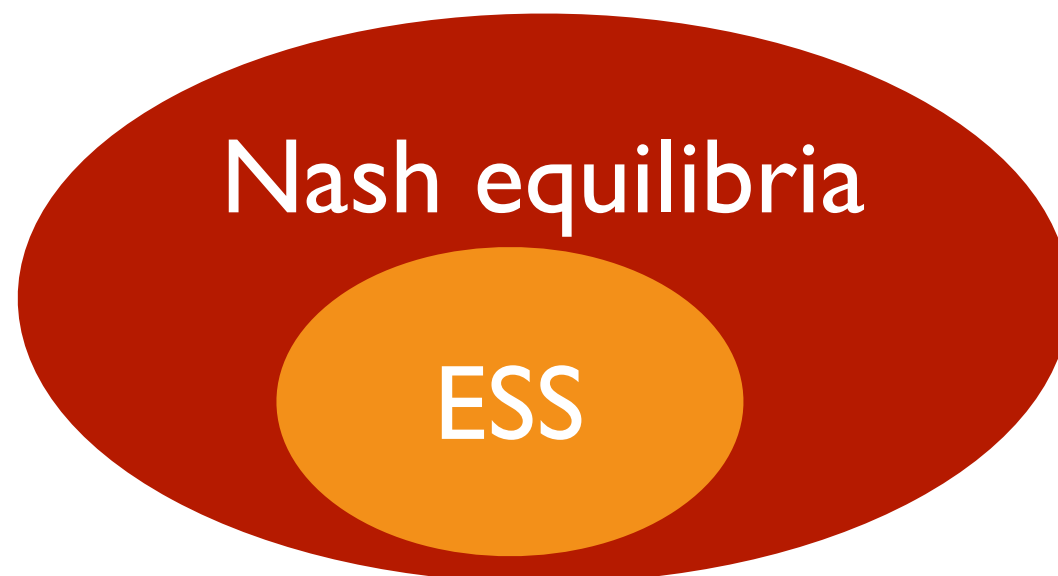
**Every ESS is an asymptotically stable fixed point of the replicator dynamics**



# Evolutionary Stable Strategies

*A strategy is an ESS if it is immune to invasion by mutant strategies, given that the mutants initially occupy a small fraction of population*

**Every ESS is an asymptotically stable fixed point of the replicator dynamics**




While a NE always exists,  
an ESS may not exist

# Prisoner's dilemma

Player 2

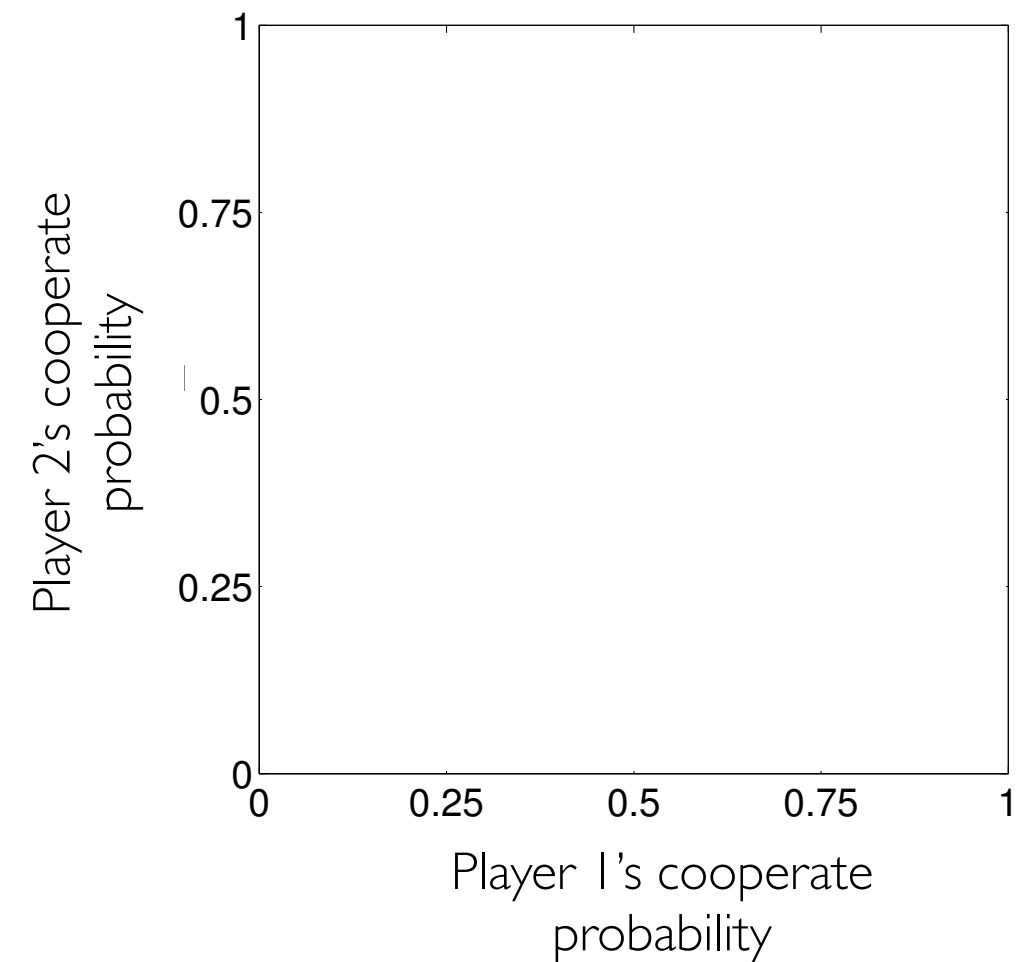
		Player 2	
		Cooperate	Defeat
Player 1	Cooperate	3,3	0,5
	Defeat	5,0	1,1

# Prisoner's dilemma

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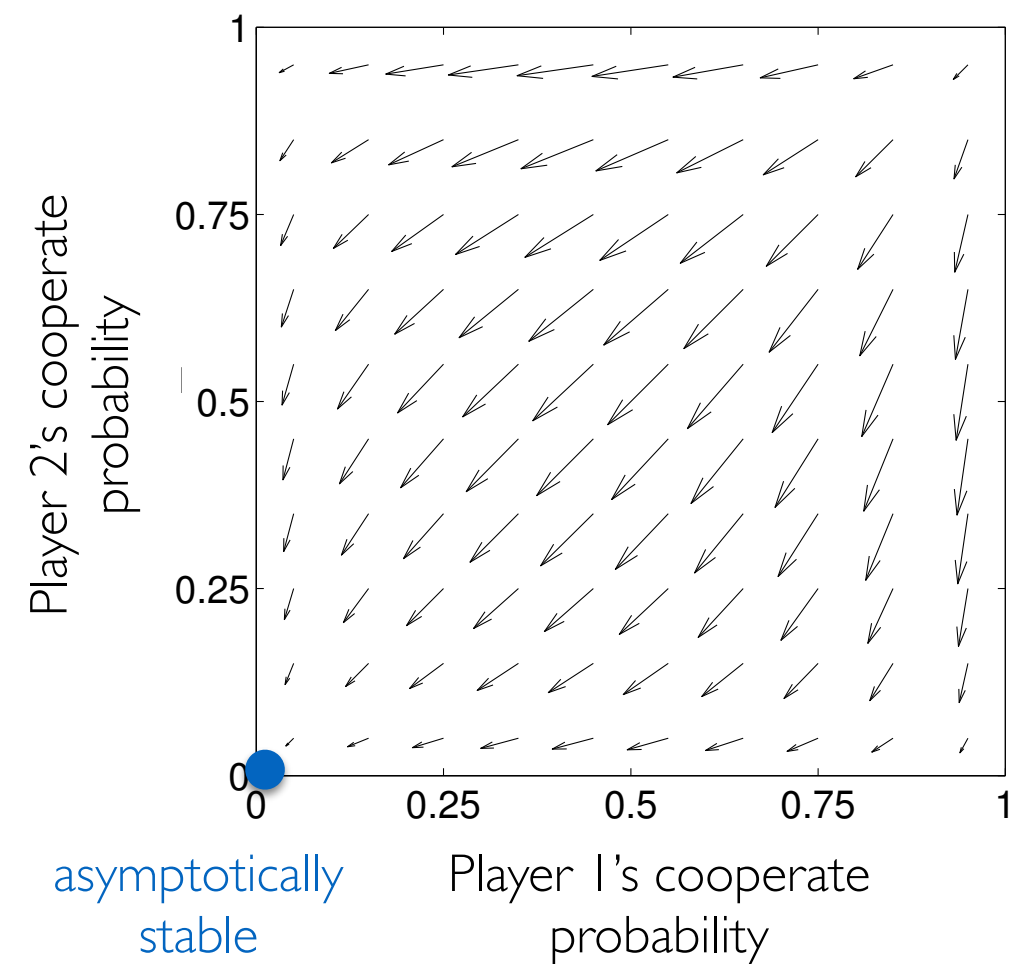
# Prisoner's dilemma

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# Prisoner's dilemma

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# Stag hunt

Player 2



Player 1

	Stag	Hare
Stag	4,4	1,3
Hare	3,1	3,3




# Stag hunt

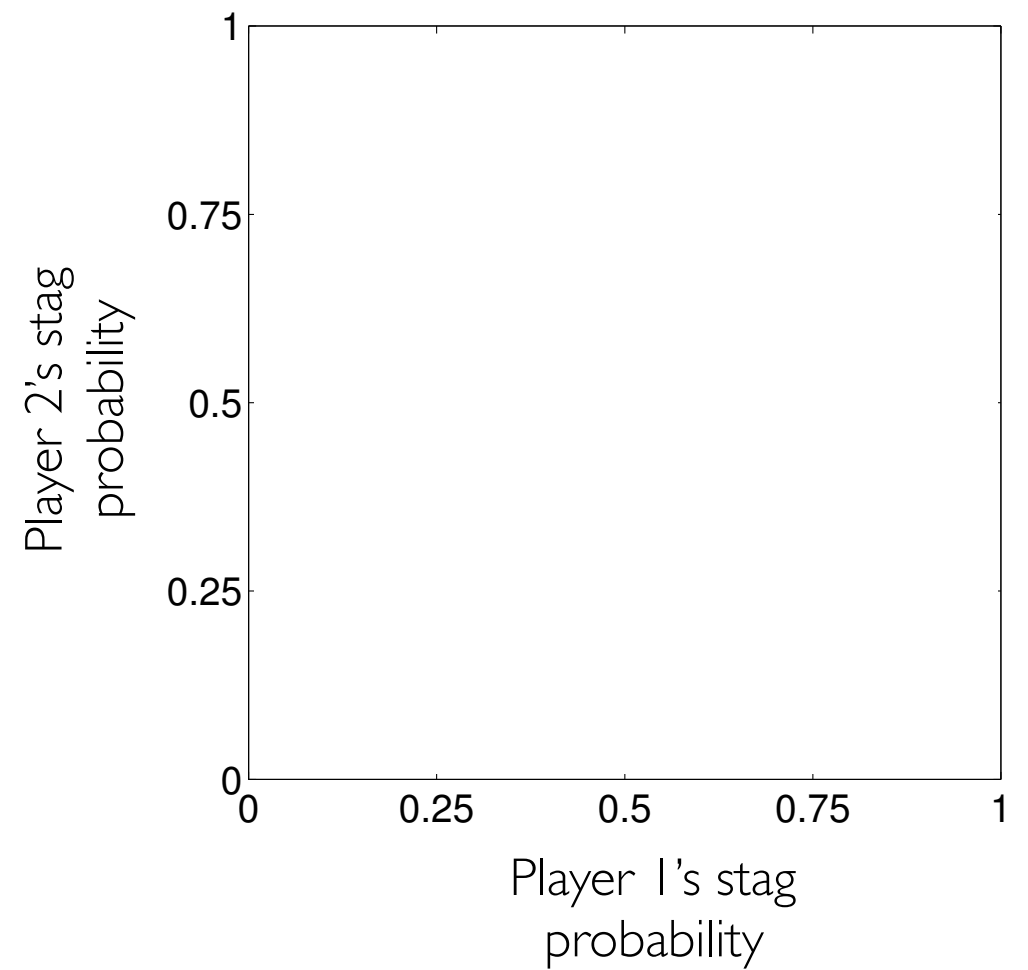
Player 2

Player 1

	Stag	Hare
Stag	 4,4	1,3
Hare	3,1	 3,3

# Stag hunt

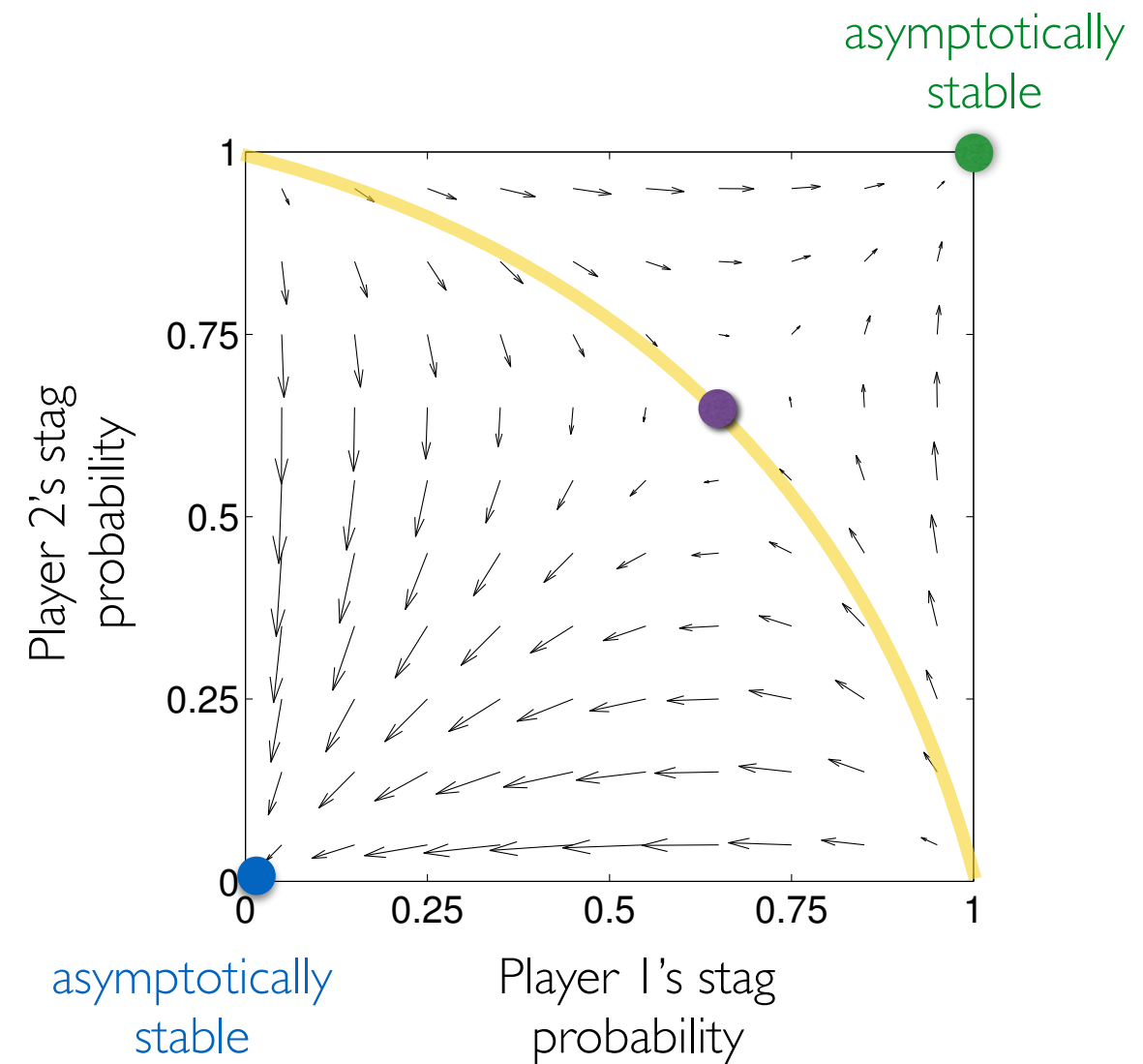
		Player 2	
		Stag	Hare
Player 1	Stag	 4,4	1,3
	Hare	 3,1	 3,3





# Stag hunt

		Player 2	
		Stag	Hare
Player 1	Stag	<div data-bbox="699 991 768 1052" style="color: green; font-weight: bold;">●</div> 4,4	1,3
	Hare	<div data-bbox="974 1226 1042 1287" style="color: purple; font-weight: bold;">●</div> 3,1	<div data-bbox="1056 1287 1138 1359" style="color: blue; font-weight: bold;">●</div> 3,3



# Matching pennies


Player 2

Player 1

	Head	Tail
Head	0,1	1,0
Tail	1,0	0,1

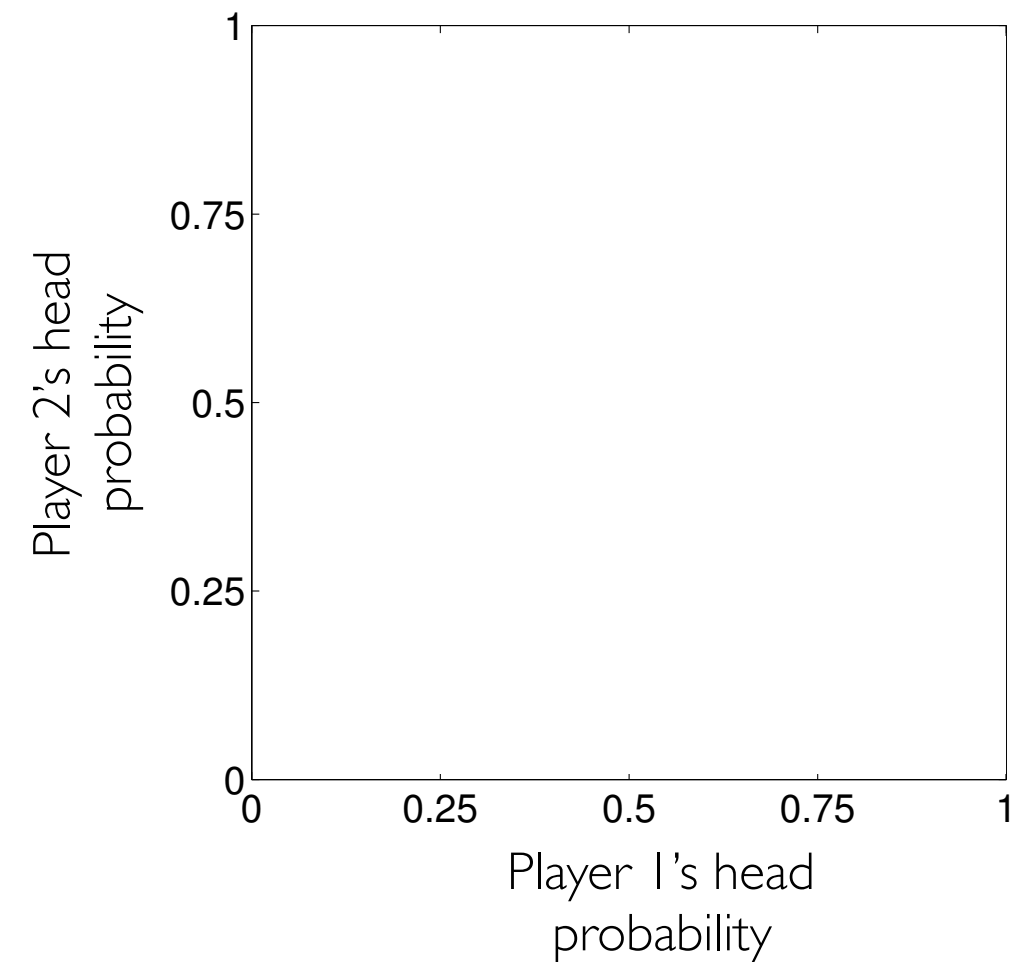
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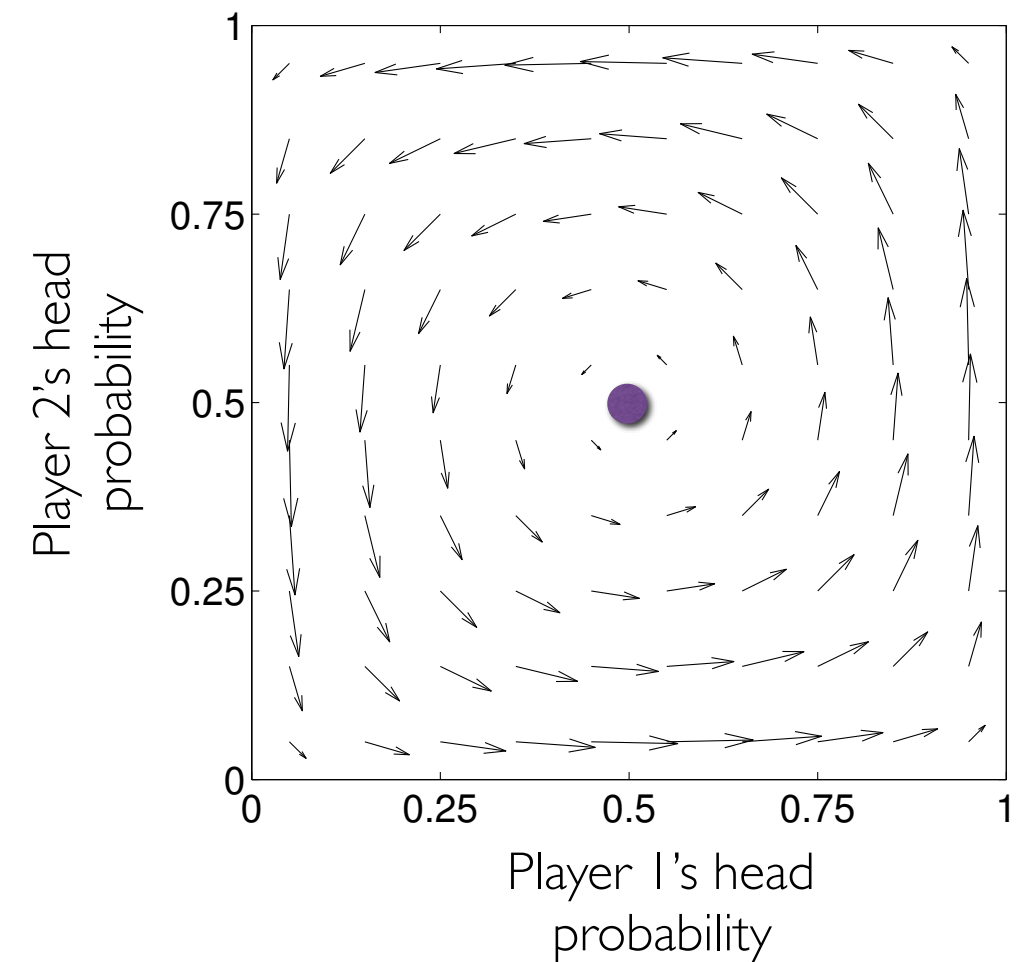
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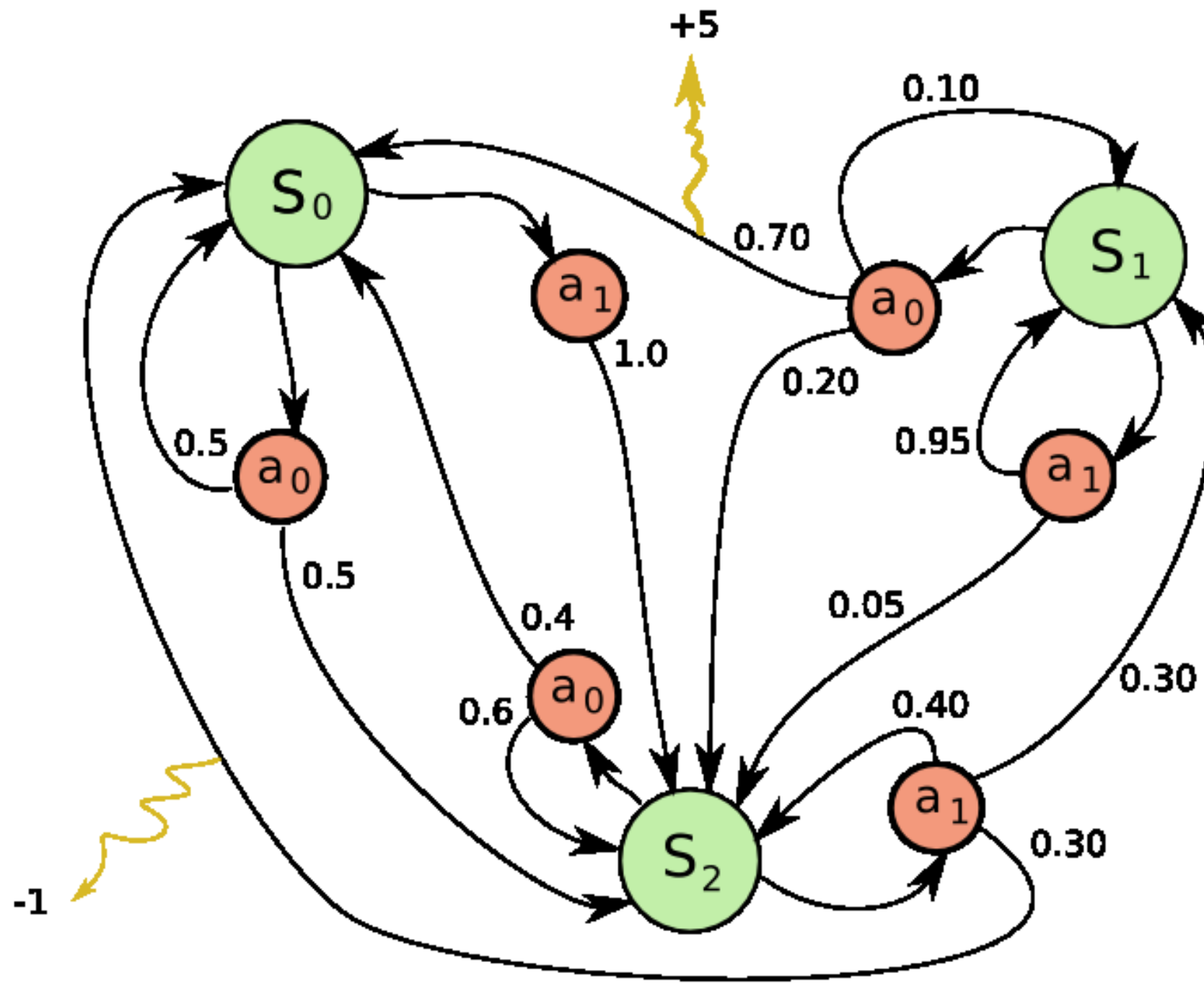
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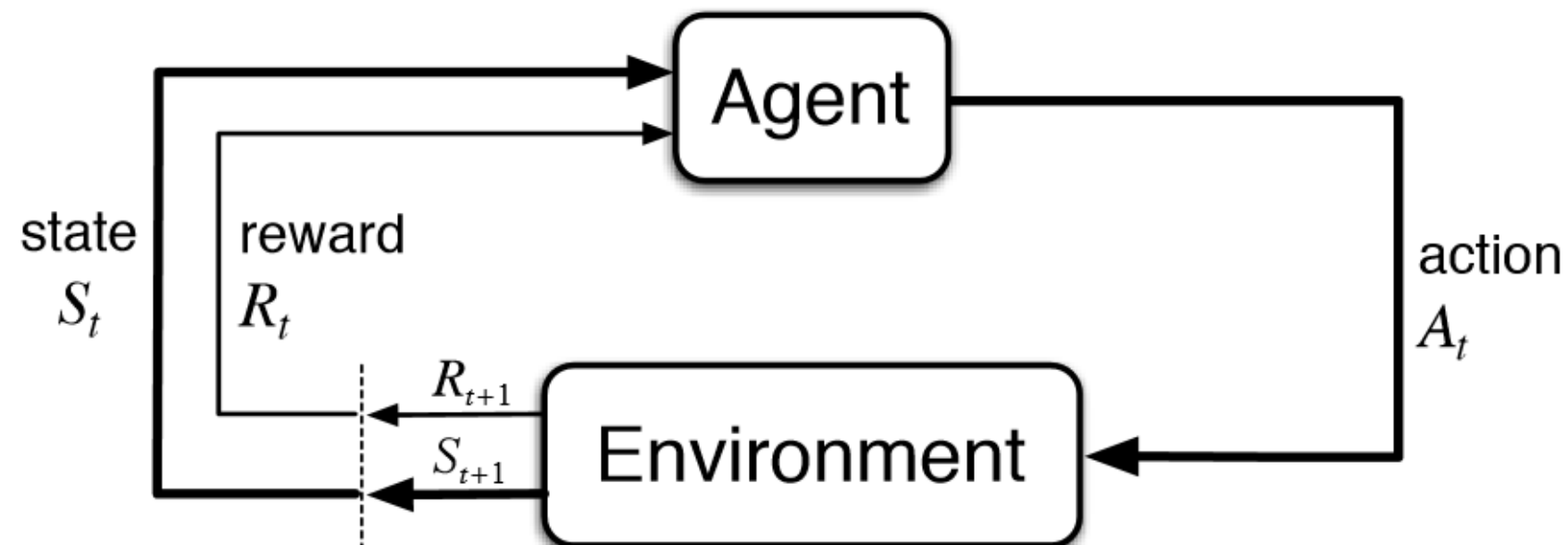


# Multi-agent learning

# Markov decision problem



# Reinforcement learning





# Q-learning (I)

For every pair state/action:

$$Q(s, a) \leftarrow Q(s, a) + \alpha \left[ r + \gamma \max_{a'} Q(s, a') - Q(s, a) \right]$$

learning rate



The diagram illustrates the components of the Q-learning update equation. Three red arrows originate from labels at the bottom and point to specific parts of the equation above. The first arrow, labeled 'learning rate', points to the Greek letter alpha (α). The second arrow, labeled 'reward', points to the variable r. The third arrow, labeled 'discount factor', points to the Greek letter gamma (γ).

reward

discount factor

# Example: normal-form games

Player 1

- 1 state
- 2 actions (Cooperate, Defeat)

Player 2

Player 1

	Player 2	
	Cooperate	Defeat
Cooperate	3,3	0,5
Defeat	5,0	1,1

# Example: normal-form games

$$Q(a) \leftarrow Q(a) + \alpha (r - Q(a)) \quad \alpha = 0.2$$

$$\sigma_1(a) = \begin{cases} 1.0 & a = \text{Cooperate} \\ 0.0 & a = \text{Defeat} \end{cases}$$
$$\sigma_1(a) = \begin{cases} 0.2 & a = \text{Cooperate} \\ 0.8 & a = \text{Defeat} \end{cases}$$

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# Example: normal-form games

$$Q(a) \leftarrow Q(a) + \alpha (r - Q(a)) \quad \alpha = 0.2$$

round	Player 2's action	Player 1's $Q$ function
$t = 0$	—	$Q(\text{Cooperate}) = 0$
$t = 1$	$a = \text{Cooperate}$	$Q(\text{Cooperate}) = 0.6$
$t = 2$	$a = \text{Defeat}$	$Q(\text{Cooperate}) = 0.48$
$t = 3$	$a = \text{Defeat}$	$Q(\text{Cooperate}) = 0.384$
$t = 4$	$a = \text{Defeat}$	$Q(\text{Cooperate}) = 0.3072$
$t = 5$	$a = \text{Defeat}$	$Q(\text{Cooperate}) = 0.24576$
$t = 6$	$a = \text{Cooperate}$	$Q(\text{Cooperate}) = 0.496608$

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# Q-learning (2)

Softmax (a.k.a. Boltzmann exploration)

$$\sigma_i(a) = \frac{\exp(Q(s, a)/\tau)}{\sum_{a'} \exp(Q(s, a')/\tau)}$$

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temperature



# Q-learning (2)

Softmax (a.k.a. Boltzmann exploration)

$$\sigma_i(a) = \frac{\exp(Q(s, a)/\tau)}{\sum_{a'} \exp(Q(s, a')/\tau)}$$

temperature



Every action is played with strictly positive probability

The larger the temperature, the smoother the function

If the temperature is 0, we would have a best response

# Example: normal-form games

$Q(\text{Cooperate})$	$Q(\text{Defeat})$	$\sigma_1(\text{Cooperate})$	$\sigma_1(\text{Cooperate})$
0	0	0.5	0.5
1	0	0.731	0.269
5	0	0.99331	0.00669
10	0	0.999955	0.000045

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# Example: normal-form games

$Q(\text{Cooperate})$	$Q(\text{Defeat})$	$\sigma_1(\text{Cooperate})$	$\sigma_1(\text{Cooperate})$
0	0	0.5	0.5
1	0	0.731	0.269
5	0	0.99331	0.00669
10	0	0.999955	0.000045

# Self-play Q-learning dynamics

# Self-play learning

Q-learning algorithm

Player 2

Q-learning algorithm

Player 1

	Cooperate	Defeat
Cooperate	3,3	0,5
Defeat	5,0	1,1

# Learning dynamics

Assumptions:

- Time is continuous
- All the actions can be selected simultaneously

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$$\dot{\sigma}_1(a, t) = \frac{\alpha \sigma_1(a, t)}{\tau} \left( e_a U_1 \sigma_2(t) - \sigma_1(t) U_1 \sigma_2(t) \right) - \alpha \sigma_1(a, t) \left( \log(\sigma_1(a)) - \sum_{a'} \sigma_1(a') \log(\sigma_1(a')) \right)$$

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exploitation term

exploration term

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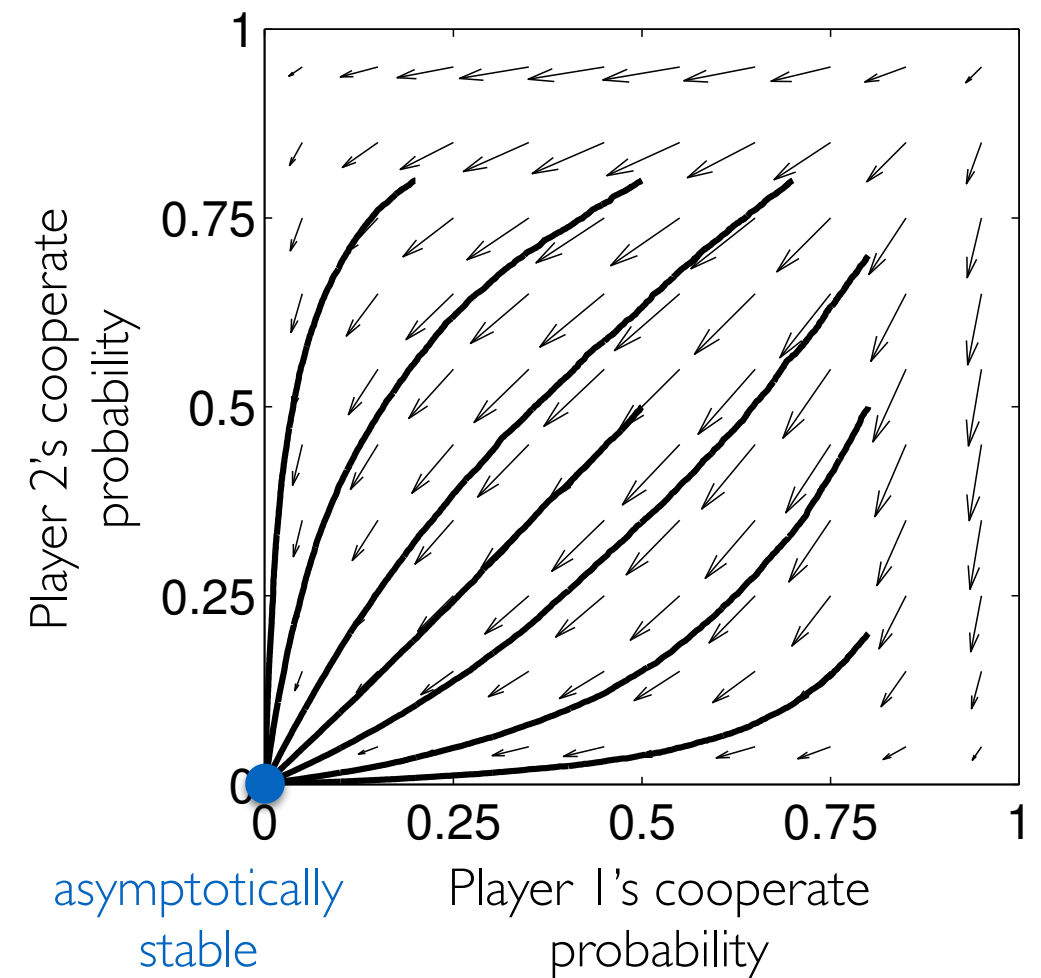
exploitation term

exploration term

When the temperature is 0, the Q-learning behaves as the replicator dynamics

# Prisoner's dilemma

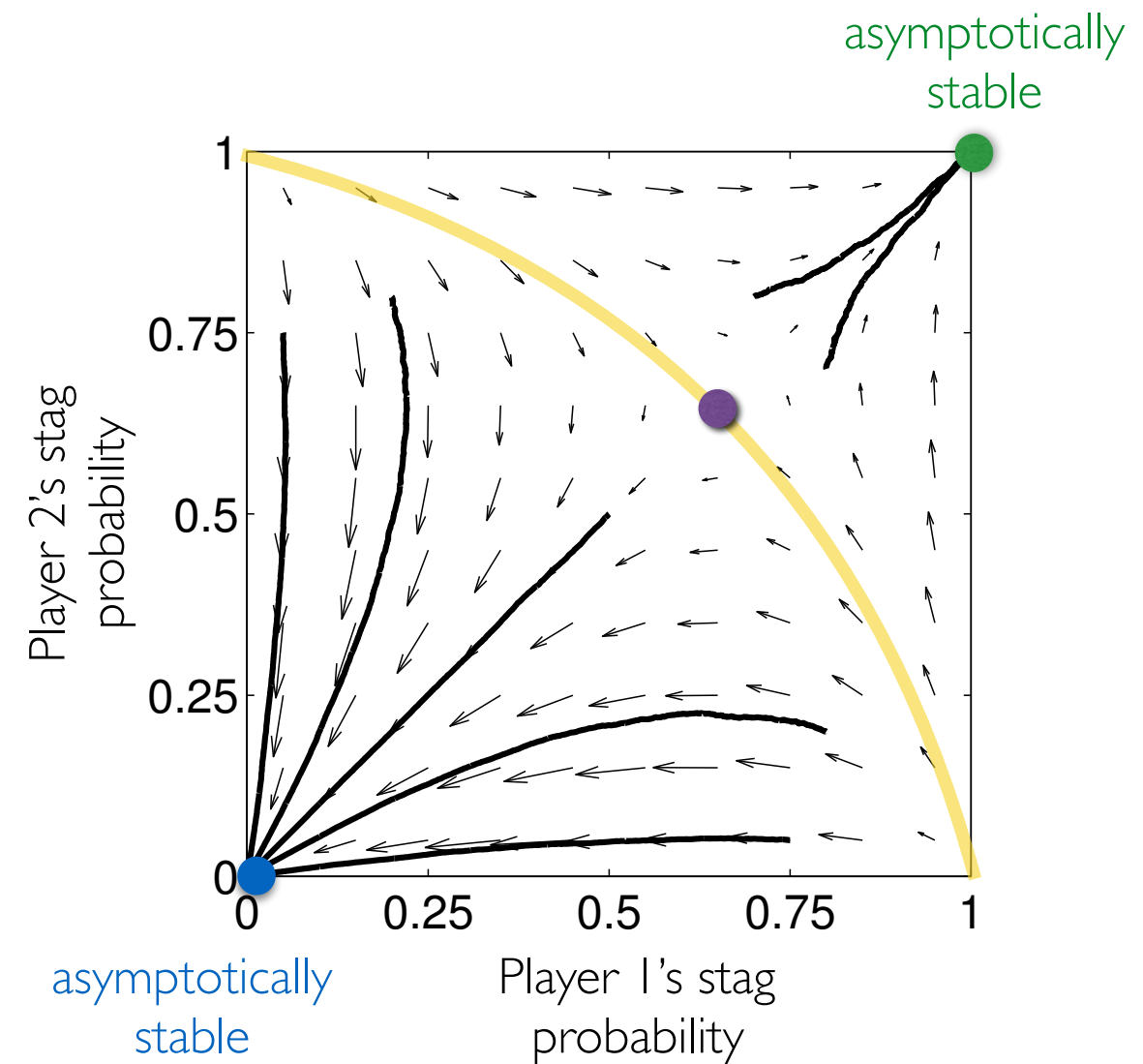
		Player 2	
		Cooperate	Defeat
Player 1	Cooperate	3,3	0,5
	Defeat	5,0	1,1





# Stag hunt

		Player 2	
		Stag	Hare
Player 1	Stag	4,4	1,3
	Hare	3,1	3,3



# Matching pennies

		Player 2	
		Head	Tail
Player 1	Head	0,1	1,0
	Tail	1,0	0,1

